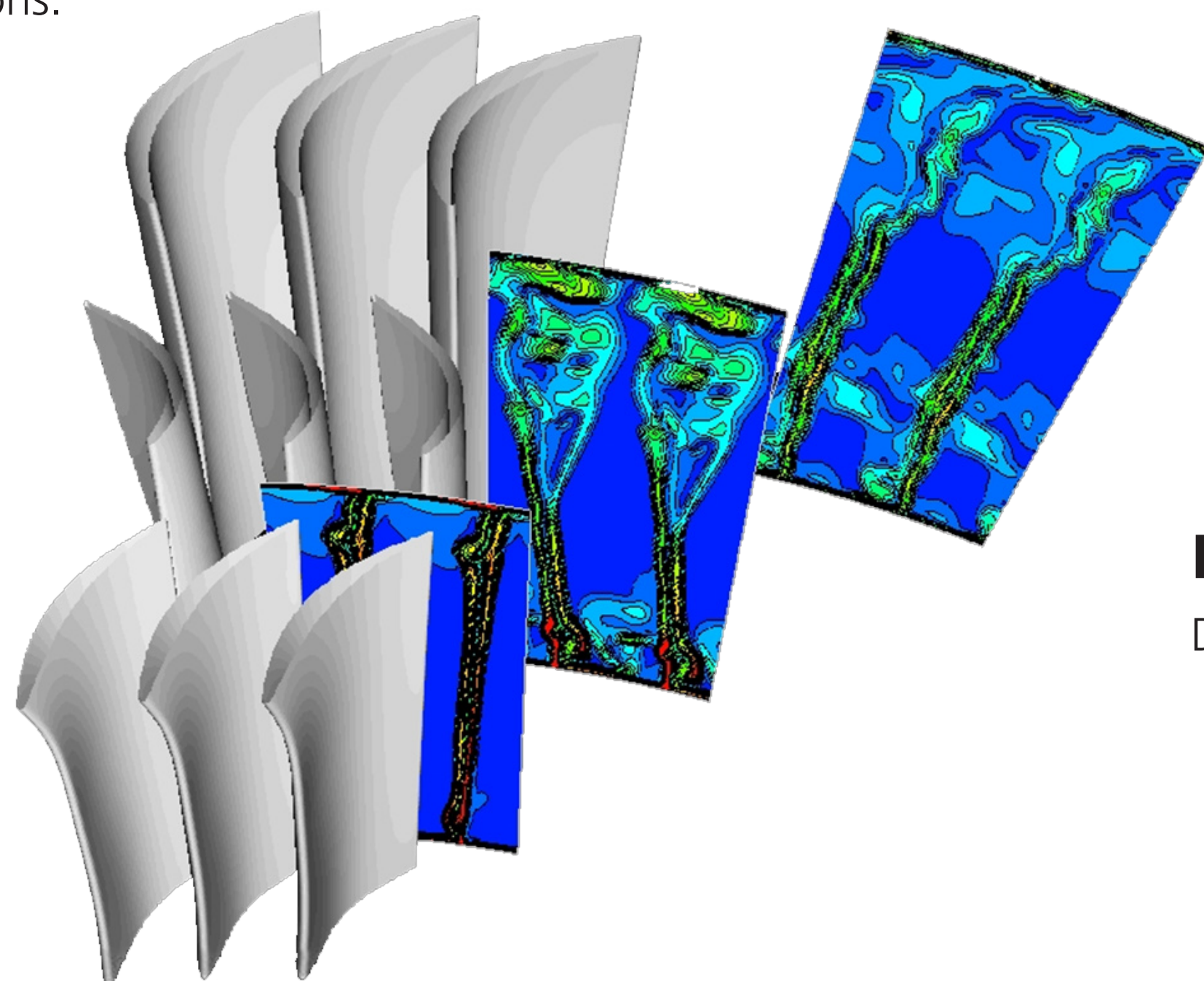




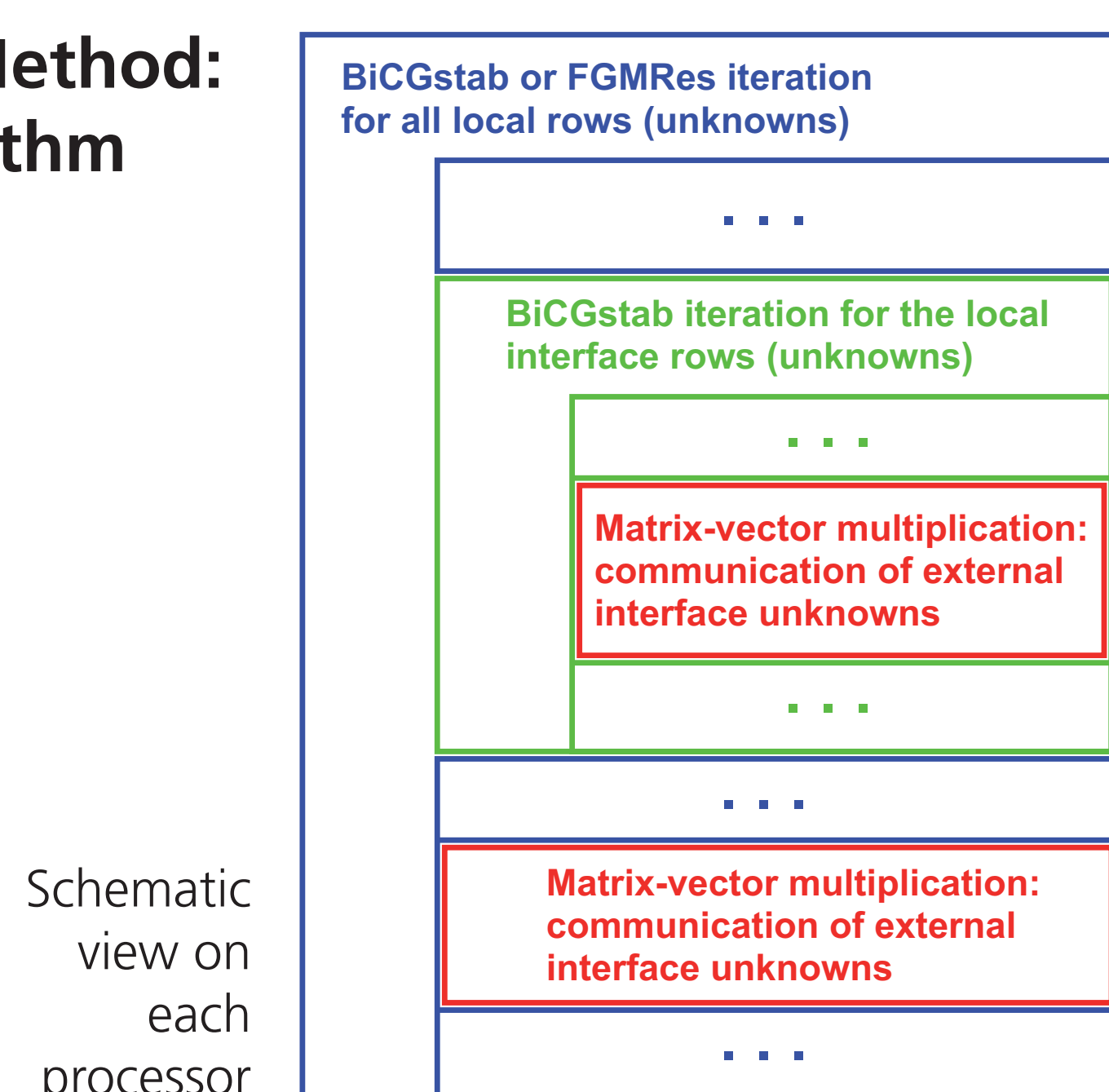
Parallel Preconditioned Iterative Solvers for Real and Complex Block-Structured CFD Problems

Parallel Simulation System TRACE

- TRACE: Turbo-machinery Research Aerodynamic Computational Environment
- Developed by the Institute for Propulsion Technology of the German Aerospace Center (DLR)
- Calculates internal turbo-machinery flows
- Finite volume method with block-structured grids
- The linearized TRACE modules require the parallel, iterative solution of large, sparse non-symmetric systems of linear equations.



DSC Method: Algorithm

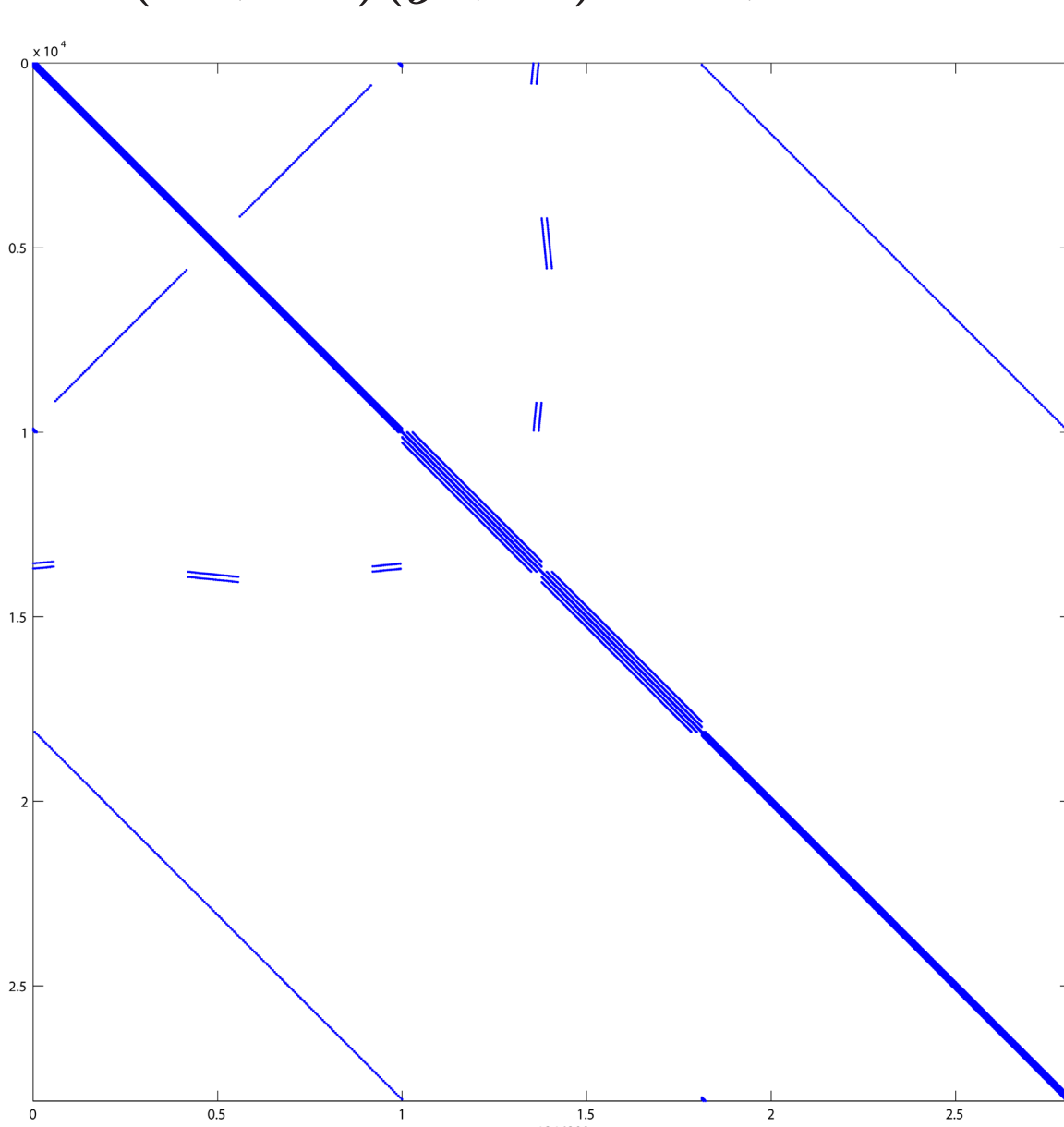


Typical linearTRACE Matrix Problem

Complex TRACE matrix
n=28,120; nz=1,246,200; condition: $6.7 \cdot 10^6$

$$Ax = b$$

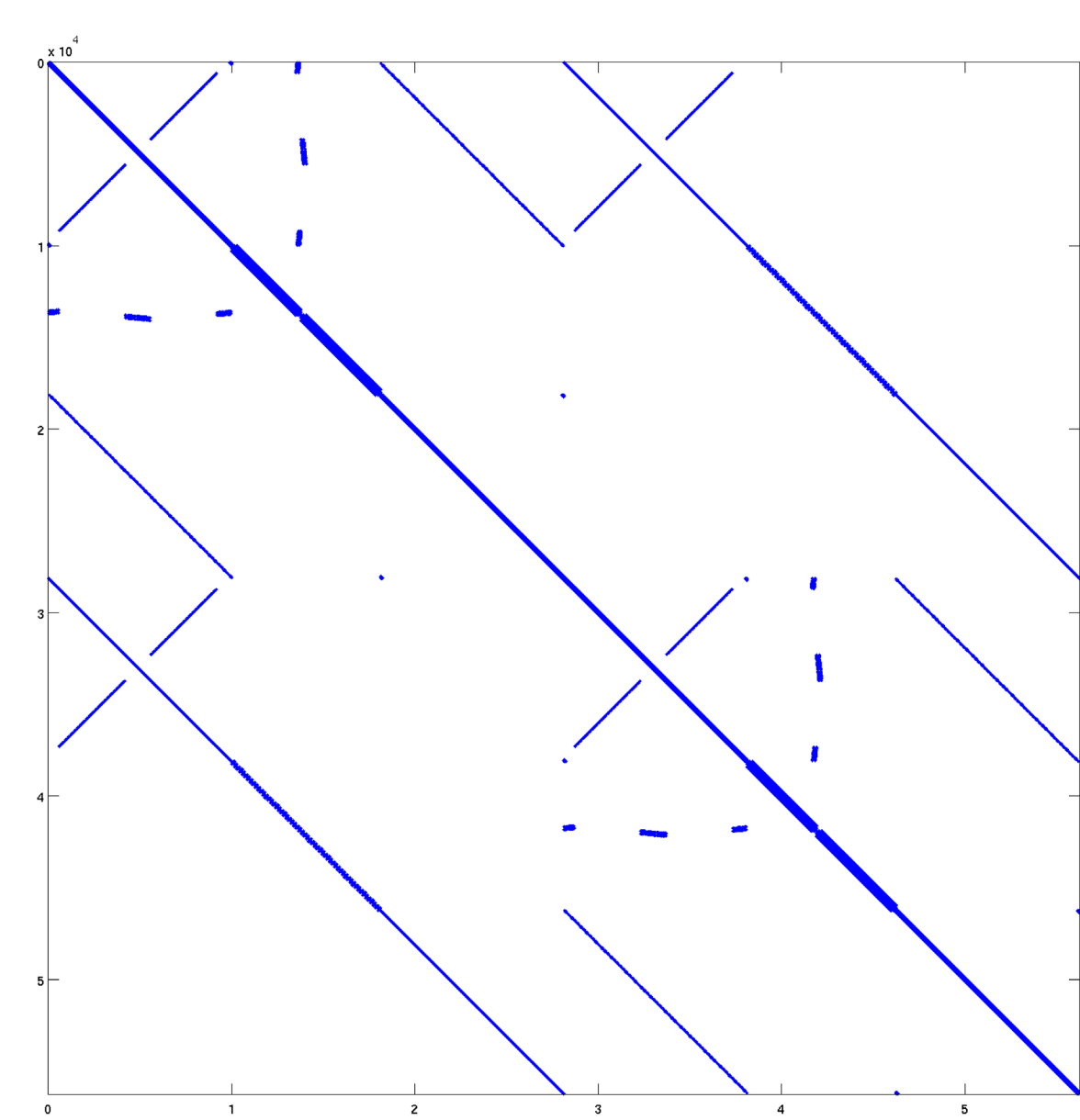
$$\Leftrightarrow (C + iD)(y + iz) = c + id$$



Real TRACE matrix
n=56,240; nz=2,572,040; condition: $8.4 \cdot 10^6$

$$\begin{pmatrix} C & -D \\ D & C \end{pmatrix} \begin{pmatrix} y \\ z \end{pmatrix} = \begin{pmatrix} c \\ d \end{pmatrix}$$

$$\Leftrightarrow Gw = e$$



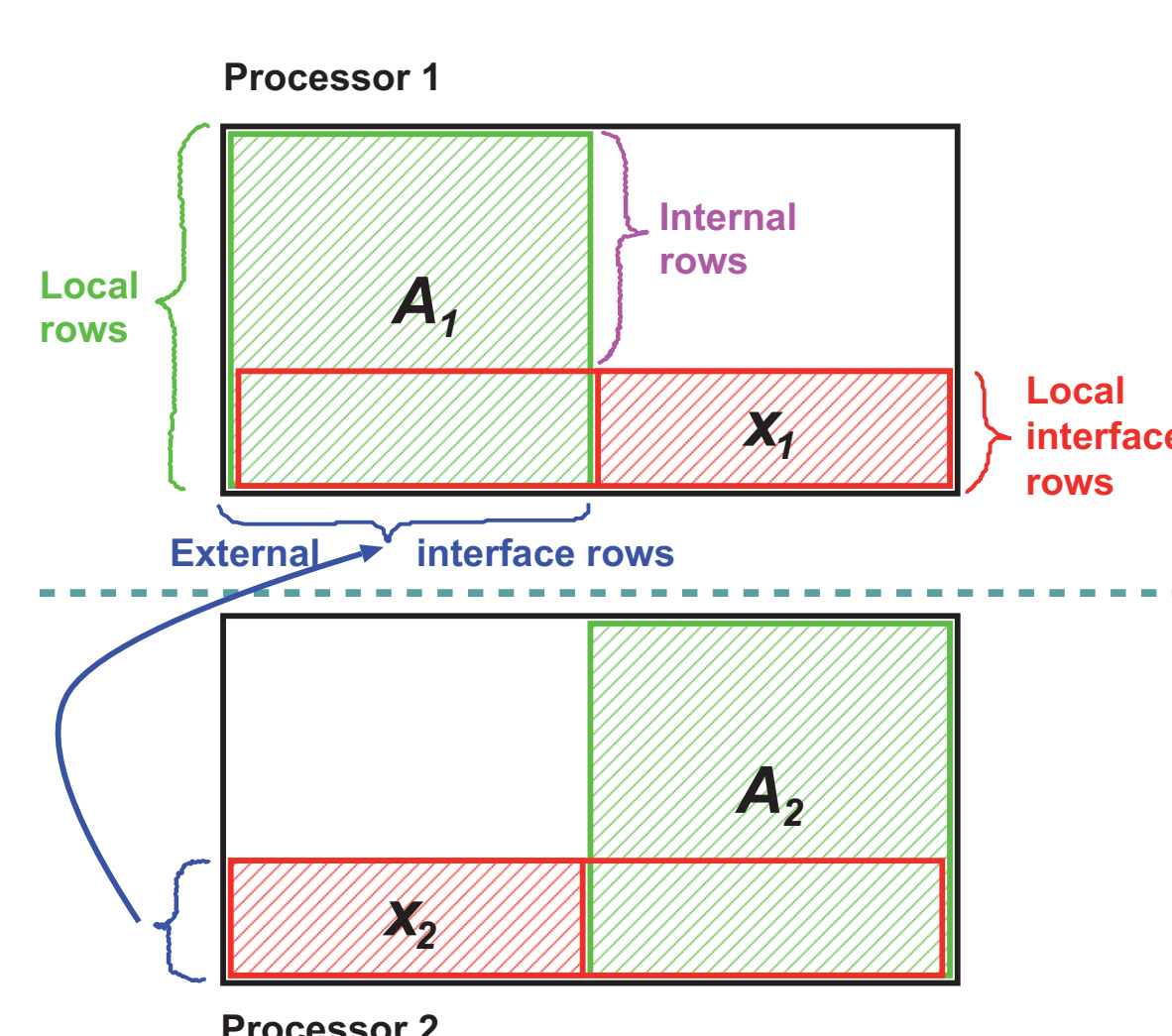
Preconditioner for TRACE: Background

- Modules *linearTRACE* or *adjointTRACE* $Ax = b$
- A non-symmetric, complex or real, sparse
- Parallel iterative solver: (F)GMRes with preconditioning $P^{-1}Ax = P^{-1}b$

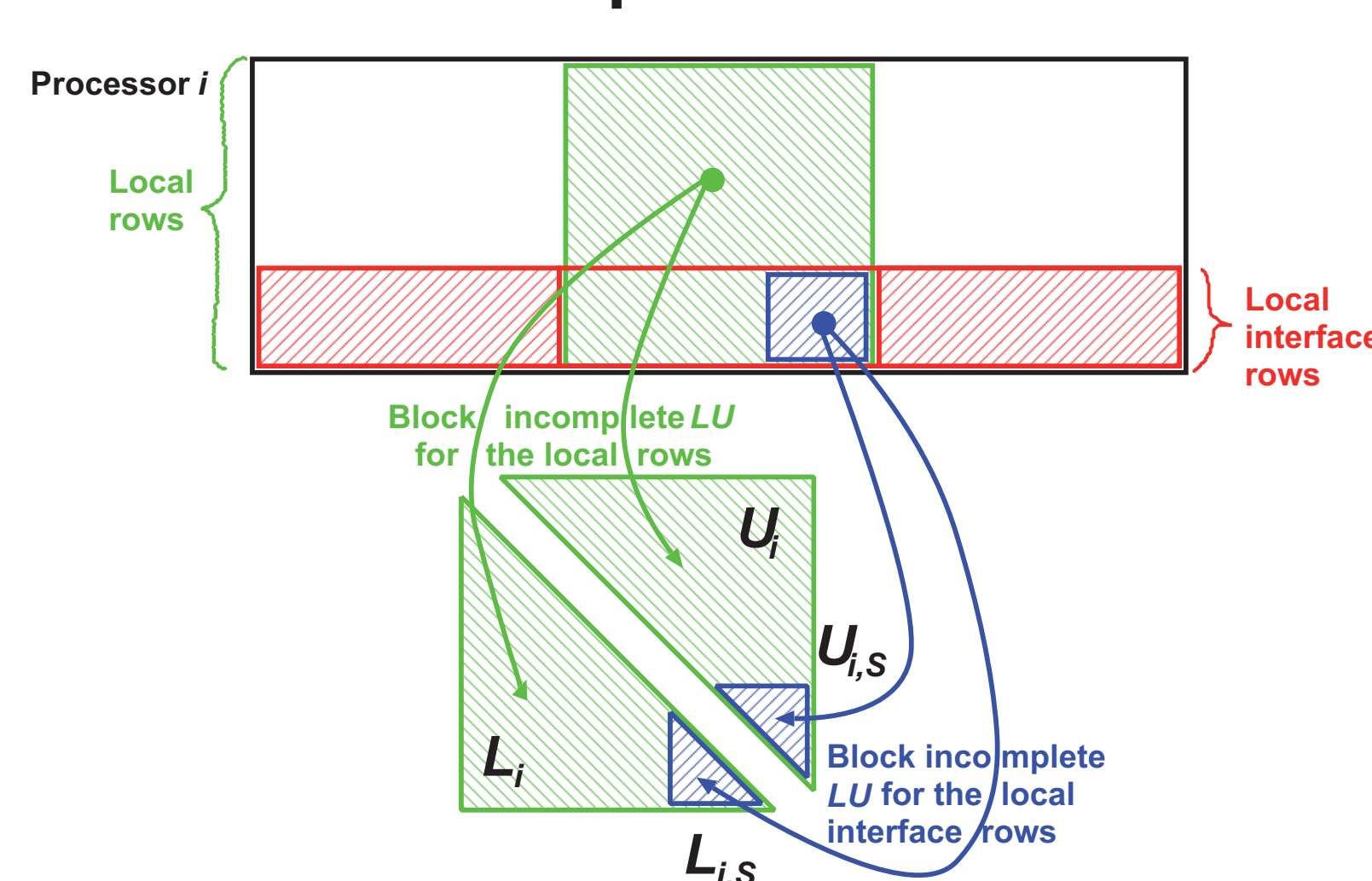
- Distinctly dominates the time behaviour
- Matrix-vector and vector-vector operations
- **Preconditioning usually is the most time-consuming operation**
 - Crucial for scalability
 - **Status:** block-local preconditioning
 - ILU, SSOR
 - **Scalability limited**
- **Goal:** global, scalable preconditioner
 - Experiments with Distributed Schur Complement (DSC) methods

DSC Method: Definitions

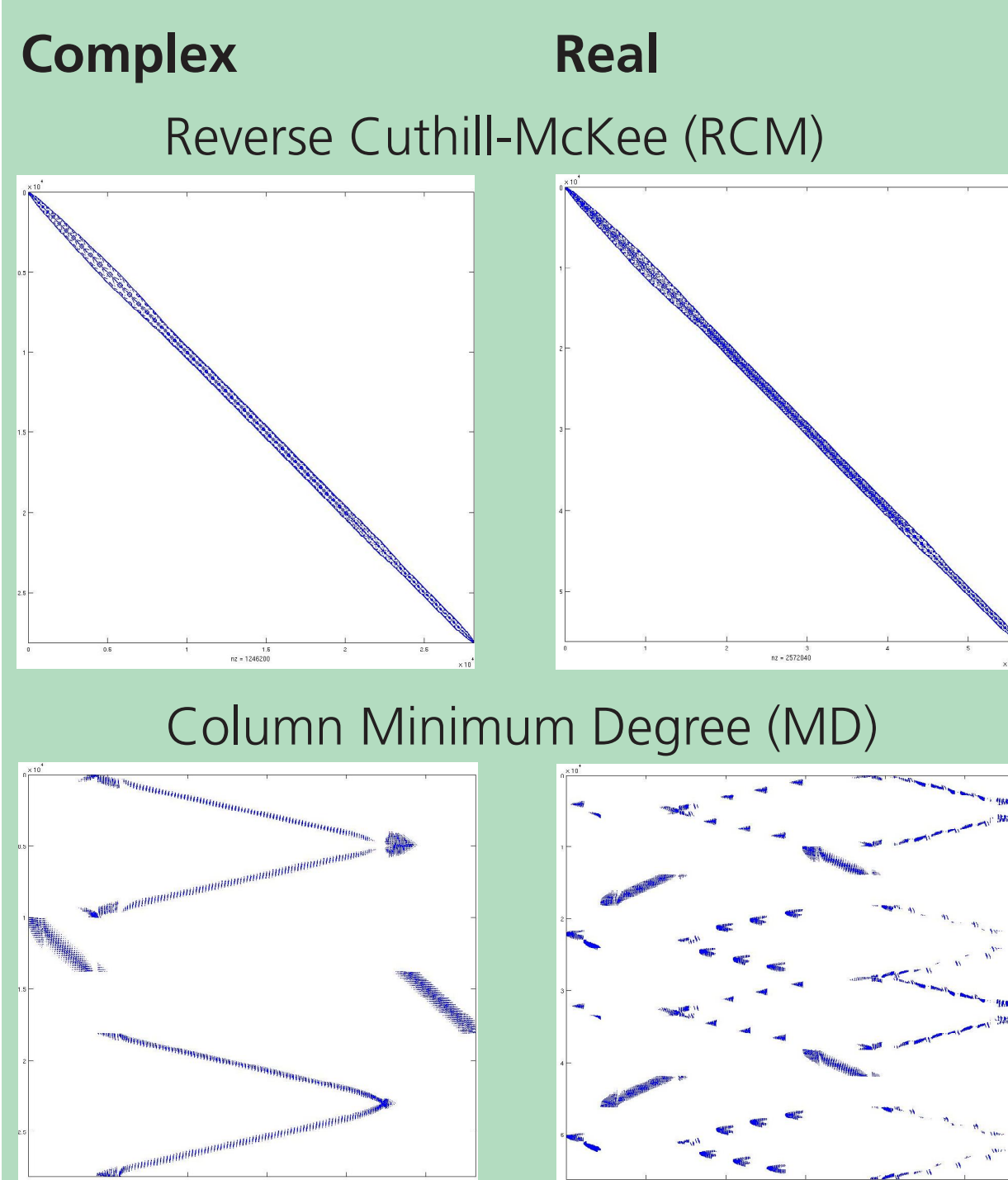
Distributed Matrix,
2 processors



DSC Method: Incomplete LU Factorizations



Matrix Permutation for Fill-in Reduction



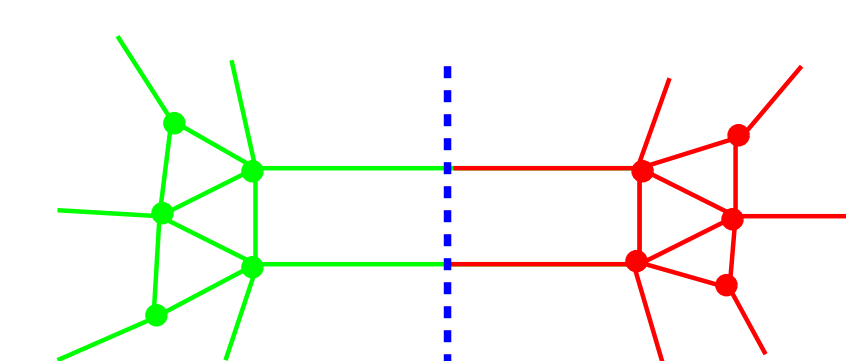
Results of the Performance Analysis for TRACE Matrix Problems

- Matrix permutations are crucial for preconditioner and iterative solver performance.
- **The ILU preconditioned iterative solvers for the complex problem formulation distinctly outperform the solvers for the real formulation.**
- **Reasons:** Complex formulation results in lower problem order, more advantageous matrix structure, has higher data locality and a better ratio of computation to memory access.

DSC Method and Partitioning

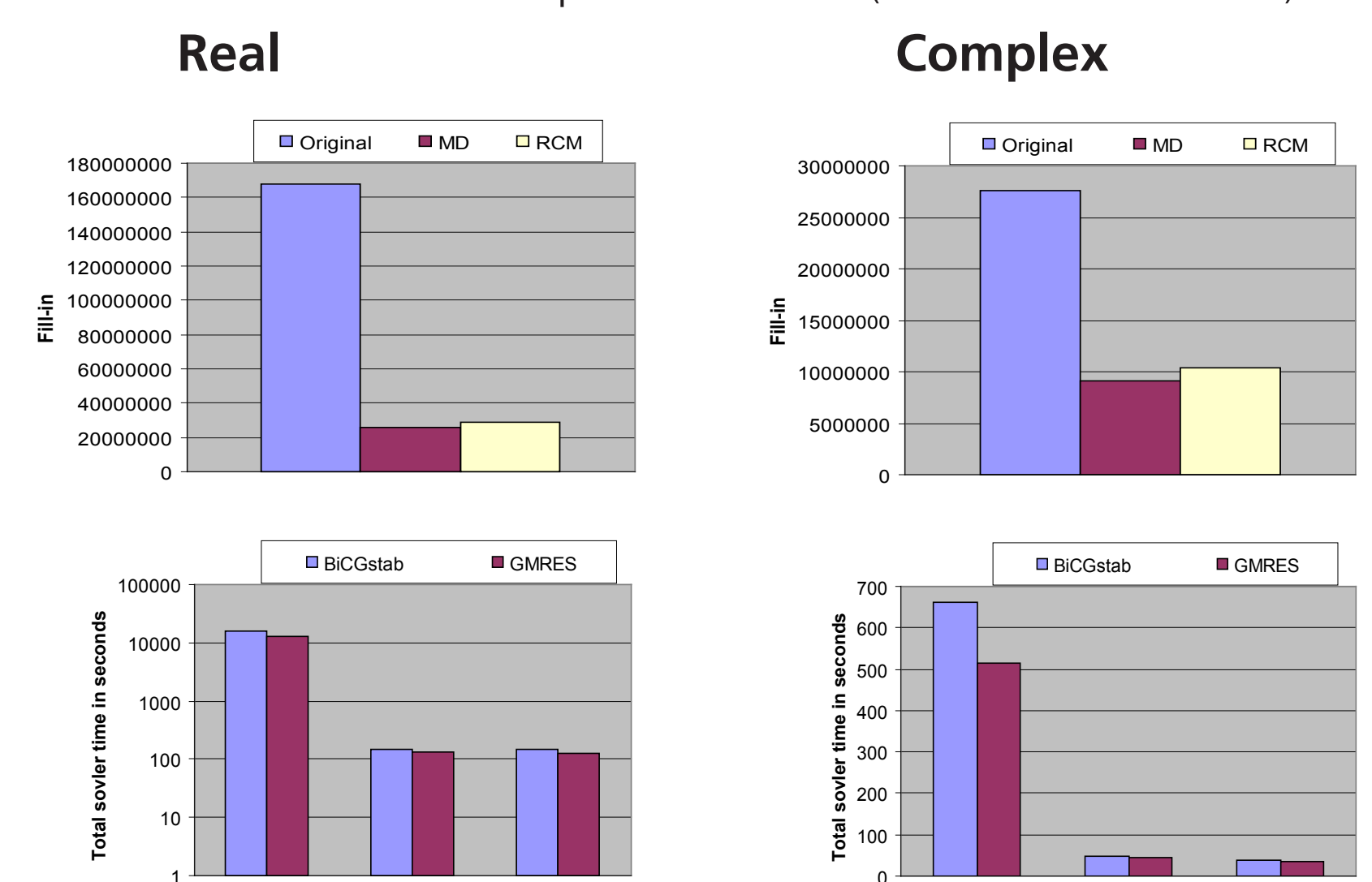
Graph partitioning: *ParMETIS* (University of Minnesota)

Goal:
Minimize the number of edges cut \leftrightarrow number of interface unknowns



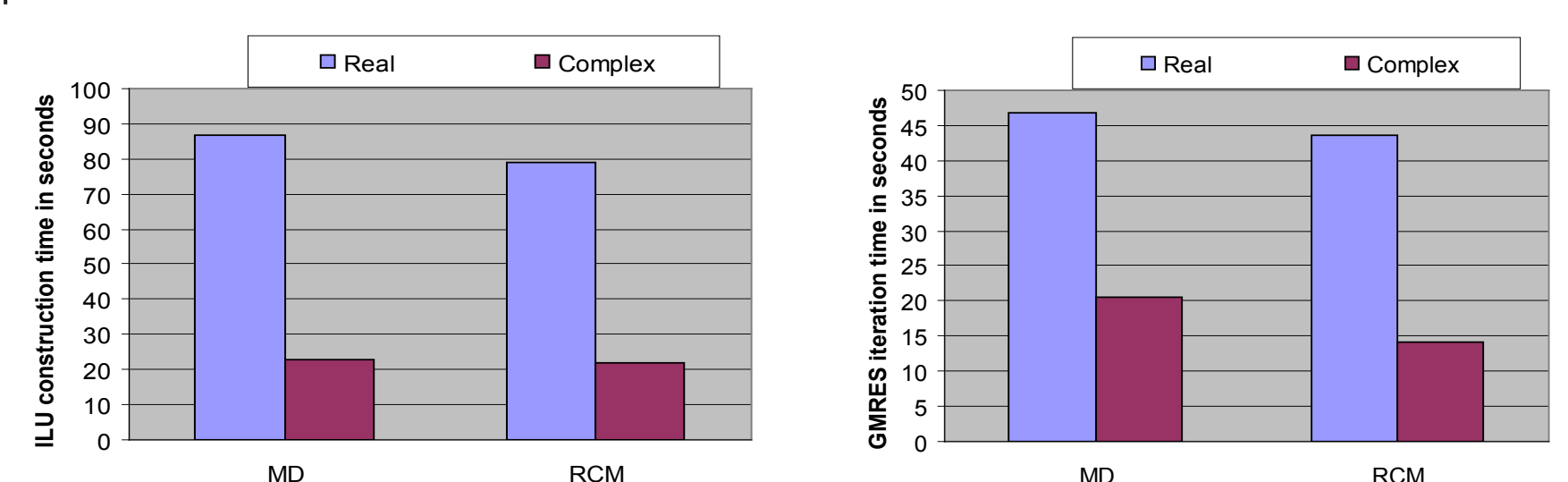
Performance Tests on a Quad-Core Intel Xeon CPU L5420 Workstation (MATLAB)

Effect of different matrix permutations (ILU threshold: 10^{-3})



Matrix permutations significantly reduce fill-in and solution time.

Comparison: GMRES preconditioned by ILU for complex and real problem formulation

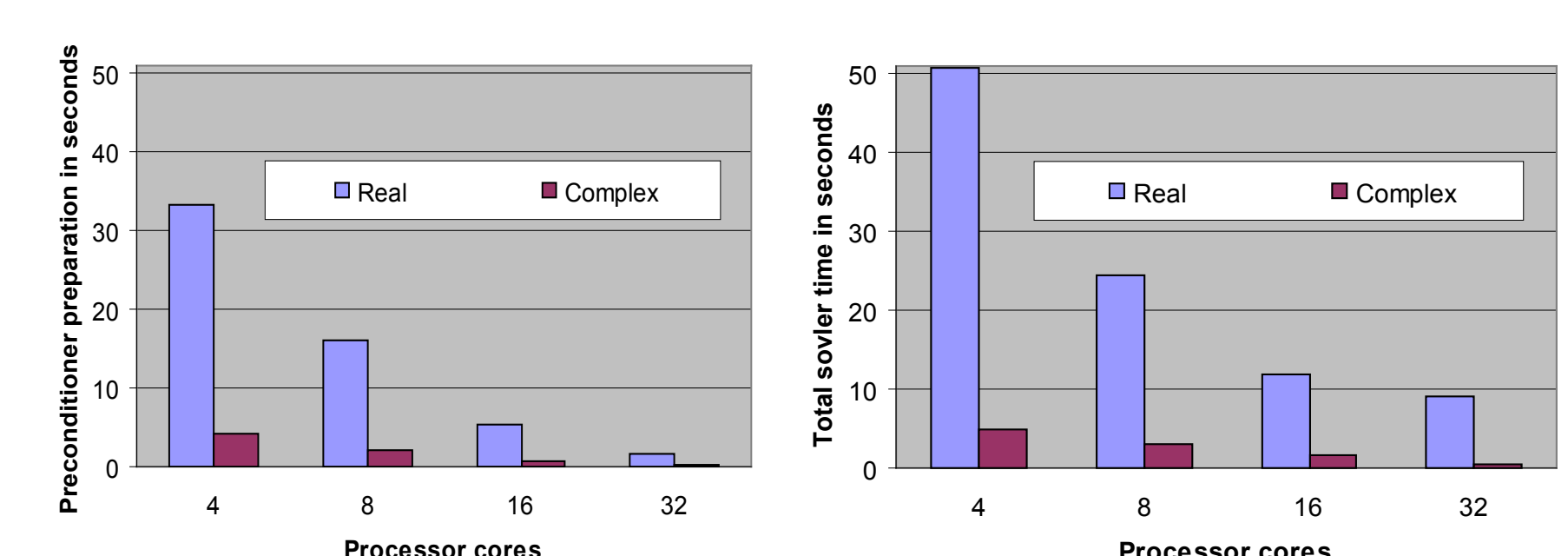


Complex formulation results in distinctly higher performance.

Performance on a Cluster at DLR

Quad-Core Intel Harpertown; 32 dual-processor nodes; 2.83 GHz

Comparison: DSC method, real vs. complex problem formulation



Performance for complex formulation is significantly superior.

